HIGH-RESOLUTION FEATURE EVALUATION BENCHMARK

Image I_3

Kai Cordes

Bodo Rosenhahn

Jörn Ostermann

Reference Benchmark for Affine Invariant Features [1]

Limitations

- ► Resolution of 0.5 megapixels
- Radial distortion
- Violated homography assumption (c. f. example)

Estimation Method

- Based on image features
- Standard homography estimation approach



Mapped I_1 to I_3

Difference Image

Contribution

New Benchmark Images with Corresponding Homographies

- ► Image resolutions: 1.5, 3, 6, and 8 megapixels
- Highly-accurate homographies
- Feature independent homography computation [2]

 $\rightarrow \textit{Differential Evolution for minimization of cost function } E(\mathtt{H})$ $\rightarrow E(\mathtt{H}) = \frac{1}{J} \sum_{j=1}^{J} d_{\mathtt{RGB}}(\mathtt{H} \cdot \mathbf{p}_{j}, \mathbf{p}'_{j})$ $\rightarrow \textit{Dense image representation}$



Example Data Set [3]: Grace



Example Result

Repeatability [4] for Feature Detectors at Different Image Resolutions

- Different results
 at different resolutions
- Lower performance at higher resolution
- ⇒ Evaluation at multiple image resolution important
- ► We provide [3]: 5 data sets





at 4 image resolutions	0 15 20 25 30 35 40 45 50 55 60 65 Viewpoint angle	0 15 20 25 30 35 40 45 50 55 60 65 Viewpoint angle
	<i>Grace</i> , 1536 × 1024	<i>Grace</i> , 3456 × 2304

[1] Krystian Mikolajczyk et al.: "A Comparison of Affine Region Detectors", IJCV 2005
[2] Kai Cordes et al.: "Increasing the Accuracy of Feature Evaluation Benchmarks Using Differential Evolution", SSCI 2011
[3] New benchmark data: http://www.tnt.uni-hannover.de/project/feature_evaluation/
[4] Repeatability matlab-code: http://www.robots.ox.ac.uk/~vgg/research/affine/





